

* UNIT - 11 *

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* CHARACTERISTICS OF OP-AMP *

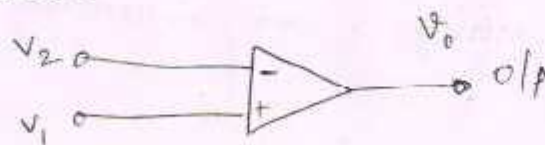
- * Ideal OP-Amp characteristics.
- * DC characteristics.
- * AC characteristics.
- * Offset voltage & current
- * Voltage series f/b & shunt f/b amplifiers.
- * Differential amplifier.
- * Frequency-response of OP-Amp.
- * Basic applications of OP-Amp — Summer, differentiator, integrator.

* Introduction :- *

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- * OP-Amp is a operational amplifier
- * It is one of the linear IC.
- * It has 2 i/p terminals, and 1 o/p terminal.

* Symbol :-



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$V_1 \rightarrow$ Non-inverting i/p terminal.

$V_2 \rightarrow$ inverting i/p terminal.

$V_o \rightarrow$ o/p terminal.

* op-Amp performs various applications such as summer, differentiator, integrator, comparator, waveform generator.

* Ideal op-Amp characteristics: *

\rightarrow open loop voltage gain, $(A_{OL}) = \text{infinity}$.

\rightarrow i/p impedance $(Z_i) = \text{infinity}$.

\rightarrow o/p impedance $(Z_o) = \text{zero}$.

\rightarrow Bandwidth (BW) = infinity.

\rightarrow zero offset (ie) $V_o = 0$; when $V_1 = 0 = V_2$.

\rightarrow Slew rate = infinity

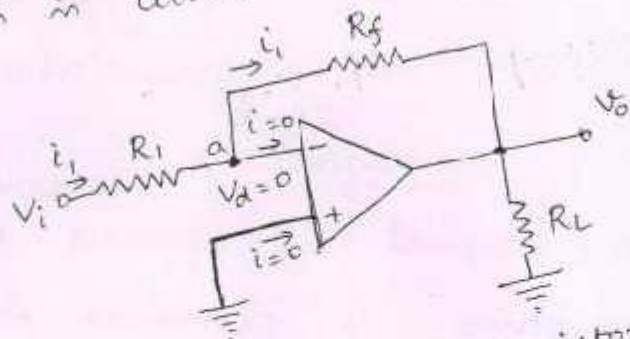
* Since i/p impedance is infinite, op-Amp draws no current from the source.

* Since gain is infinite, so the voltage b/w inverting & non-inverting i/p terminals is zero.



* Inverting Amplifier :- *

when the i/p is given to the inverting terminal of the op-amp, then the o/p is in 180° phase shift. This is called inverting amplifier.



$$i_1 = \frac{V_i}{R_1}$$

$$V_o = -i_1 R_f$$

$$\frac{V_o}{V_i} = -\frac{R_f}{R_1}$$

$R_f \rightarrow$ feedback Resistor.

$R_L \rightarrow$ Load Resistor.

- * Important points for -ve i/b ckts :- *
- \rightarrow The current drawn by either of the i/p terminal is negligible.
 - \rightarrow The differential voltage V_d b/w inverting & non-inverting i/p term must be zero.
- For non-inverting i/p terminal, closed loop voltage gain will be

$$A_{cl} = \frac{V_o}{V_i} = -\frac{R_f}{R_i} \rightarrow \textcircled{1}$$

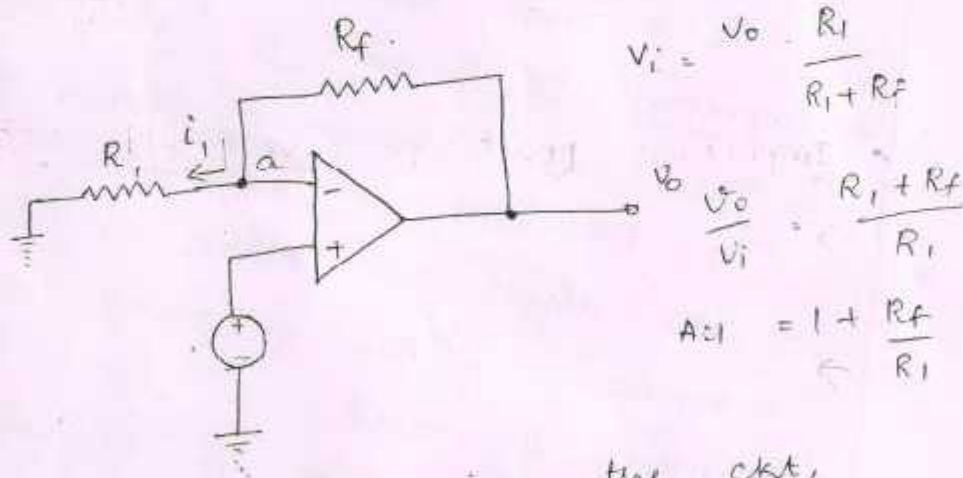
-ve sign indicates the phase shift of 180° b/w V_i and V_o .

Eqn $\textcircled{1}$ is very much useful in application such as integrator & differentiator.

* Non-inverting amplifier *

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If the signal is applied to the non-inverting i/p terminal it is called non-inverting amplifier.



$$V_i = V_o \cdot \frac{R_i}{R_i + R_f}$$

$$\frac{V_o}{V_i} = \frac{R_i + R_f}{R_i}$$

$$A_{cl} = 1 + \frac{R_f}{R_i}$$

Thus by simplifying the ckt, closed loop gain will be,

$$A_{cl} = \frac{V_o}{V_i} = 1 + \frac{R_f}{R_i}$$

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* Dc characteristics :- *

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→ An ideal op-amp draws no current from the source & its response is also independent of temperature.

→ But real op-amp draws current.

→ Also 2 i/p's respond differently to current and voltage due to mismatch in transistors.

→ These non-ideal Dc characteristics that add error to the Dc o/p voltage are

- * I/p bias current
- * i/p offset current
- * i/p offset voltage
- * Thermal drift

① - I/p bias current :-

→ The op-amp's i/p terminal is made up of BJT / FET.

→ we must give external bias current

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to base region, in order to operate in linear region.

→ But practically i/p terminals draw small value of DC current to bias the transistors.

→ The base current entering into the inverting & non-inverting i/p terminals are I_B^- & I_B^+ respectively.

→ I_B^+ , I_B^- are not exactly equal, because of internal imbalances.

→ So average value
$$I_B = \frac{I_B^+ + I_B^-}{2}$$

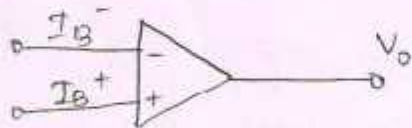


fig (a) i/p bias current.

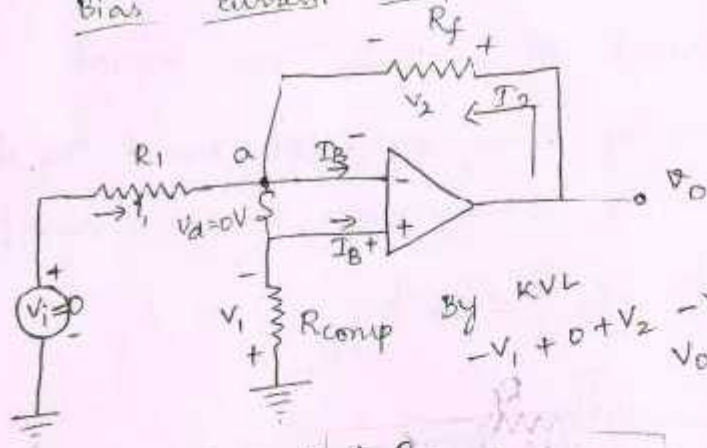
→ Due to bias current, when the i/p is zero, the o/p voltage will be some several millivolts ^{Volt}.

→ This is unacceptable for some applications where signal levels are measured.

→ This is compensated by means of using

compensated resistor.

Bias current compensation:-



$$V_1 = I_{B^+} R_{comp}$$

$$I_{B^+} = \frac{V_1}{R_{comp}}$$

$$I_1 = \frac{V_1}{R_1}$$

$$I_2 = \frac{V_2}{R_f}$$

$$I_{B^-} = I_2 + I_1 = \frac{V_2}{R_f} + \frac{V_1}{R_1} = V_1 \left[\frac{R_1 + R_f}{R_f R_1} \right]$$

Assume $I_{B^+} = I_{B^-}$

$$V_1 \left[\frac{R_1 + R_f}{R_f R_1} \right] = \frac{V_1}{R_{comp}}$$

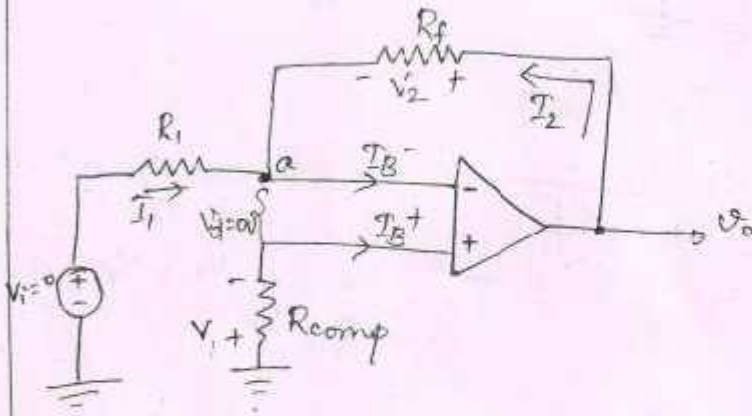
$$R_{comp} = \frac{R_f \cdot R_1}{R_1 + R_f}$$

① Input offset current :- *

→ Bias current compensation will work, when both bias currents (I_B^+ & I_B^-) are equal.

→ But both of them are not equal. The diff. b/w both of them gives offset current (I_{os})

$$|I_{os}| = |I_B^+| - |I_B^-|$$



From above figure,

$$V_1 = I_B^+ \cdot R_{comp}$$

$$I_1 = \frac{V_1}{R_1}$$

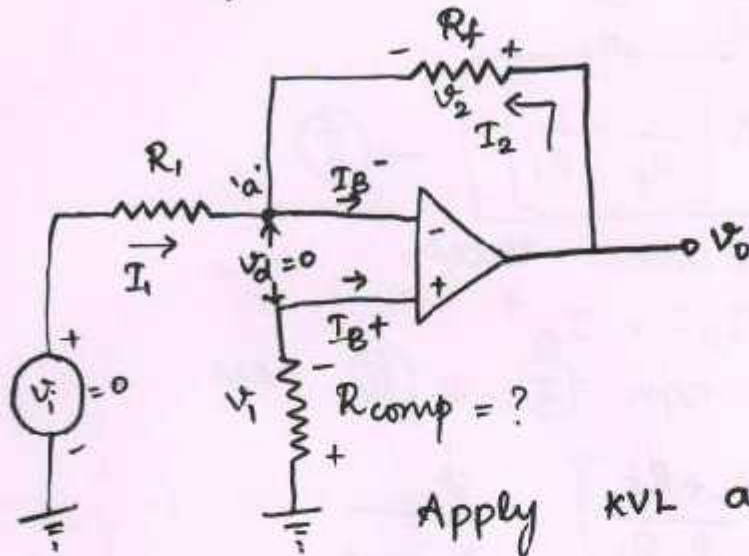
Kcl at node 'a'

$$I_2 = I_B^- - I_1 = I_B^- - \left[I_B^+ \left(\frac{R_{comp}}{R_1} \right) \right] \rightarrow \text{A}$$

$$V_o = I_2 R_f - V_1$$

$$= I_2 R_f - I_B^+ R_{comp} \rightarrow \text{B}$$

Compensating N/w ∴ *



Apply KVL at i/p ckt,

$$-V_i + 0 + V_2 - V_o = 0$$

$$\boxed{V_o = V_2 - V_i} \rightarrow \textcircled{1}$$

* To find R_{comp} ∴ *

$$V_i = I_{B+} \cdot R_{comp} \Rightarrow \boxed{I_{B+} = \frac{V_i}{R_{comp}}} \rightarrow \textcircled{I}$$

$$\textcircled{4} \leftarrow \boxed{I_1 = \frac{V_i}{R_1}} ; I_2 = \frac{V_2}{R_f} \rightarrow \textcircled{2}$$

W.K.T, $V_o = 0$ for $V_i = 0$

sub this in eqn ① $\boxed{V_2 = V_i} \rightarrow \textcircled{3}$

sub eqn ③ in eqn ②.

$$\boxed{I_2 = \frac{V_i}{R_f}} \rightarrow \textcircled{5}$$

$$I_B^- = I_a + I_1 \quad \text{sub eqn (4) \& (5) here}$$
$$= \frac{V_1}{R_f} + \frac{V_1}{R_1}$$

$$I_B^- = V_1 \left[\frac{1}{R_f} + \frac{1}{R_1} \right] \rightarrow \textcircled{\text{II}}$$

Let us assume that,

$$I_B^- = I_B^+$$

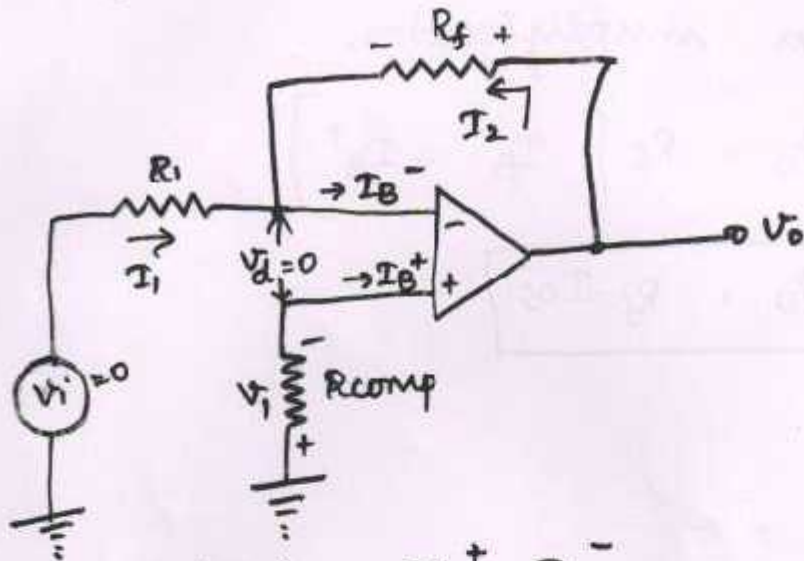
sub eqn $\textcircled{\text{I}}$ & $\textcircled{\text{II}}$, here,

$$V_1 \left[\frac{R_1 + R_f}{R_1 R_f} \right] = \frac{V_1}{R_{\text{comp}}}$$

From this,

$$R_{\text{comp}} = \frac{R_1 R_f}{R_1 + R_f}$$

* I/P offset current :- *



$$|I_{os}| = I_B^+ - I_B^-$$

$$V_1 = I_B^+ \cdot R_{comp} \rightarrow \textcircled{1}$$

$$I_1 = V_1 / R_1 \rightarrow \textcircled{2}$$

KCL at node 'a' gives,

$$I_1 + I_2 = I_B^-$$

$$I_2 = I_B^- - I_1 \rightarrow \text{sub eqn } \textcircled{2} \text{ here.}$$

$$= I_B^- - \frac{V_1}{R_1} \Rightarrow \text{sub eqn } \textcircled{1} \text{ here.}$$

$$I_2 = I_B^- - I_B^+ \cdot \frac{R_{comp}}{R_1}$$

w. k. T,

$$V_o = V_2 - V_1$$

$$= I_2 \cdot R_f - V_1$$

$\textcircled{2}$ or $\textcircled{1}$ respectively

$$V_o = \left[I_B^- - I_B^+ \cdot \frac{R_{comp}}{R_1} \right] R_f - I_B^+ \cdot R_{comp}$$

After simplification,

$$V_o = R_f \left[I_B^- - I_B^+ \right]$$

$$V_o = R_f \cdot I_{os}$$

Sub eqn (A) in eqn (B)

$$V_o = I_B \left[I_B^- - I_B^+ \cdot \frac{R_{comp}}{R_1} \right] R_f - I_B^+ R_{comp}$$
$$= I_B^- R_f - I_B^+ \cdot \frac{R_{comp} R_f}{R_1} - I_B^+ R_{comp}$$

Sub $R_{comp} = \frac{R_1 R_f}{R_1 + R_f}$ & simplify.

$$V_o = R_f (I_B^- - I_B^+)$$

$$V_o = R_f \cdot I_{os}$$

The effect of offset current can be minimized by keeping fb resistances small.

iii Input offset voltage:- *

→ Though we provide many compensation techniques, the o/p voltage will not be zero, when the i/p is zero.

→ This can be made zero, by applying small voltages at the i/p terminal, so that the o/p voltage is zero.

→ This voltage is called I/p offset voltage (V_{os})

iv Thermal Drift:- *

Bias current, offset current, offset voltage change with temperature.

* A ckt null'd at 25°C , but may not be so when the temperature is 35°C . This is called drift.

* offset current drift is expressed in $\text{nA}/^{\circ}\text{C}$ & offset voltage drift in $\text{mV}/^{\circ}\text{C}$.

minimization method:-

- careful printed circuit board
- forced air cooling.

* Ac characteristics :- *

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* In Dc characteristics we find I_{IP} bias current, I_{IP} offset current, I_{IP} offset voltage, Thermal drift.

* If we want to find the response of op in the form of small s/l (or) high freq. signal, Ac characteristics of op-Amp must be known.

* Main Ac characteristics are

- Frequency Response
- ~~Bandwidth~~ Slew Rate. ←

* Frequency response :- *

→ Ideal op-Amp has Infinite bandwidth.

(i) If open loop gain is 90dB for Dc s/l

then the same $90\text{dB}^{\text{gain}}$ is maintained for AC op of op-Amp which is small to high frequency signal.

* But practical op-Amp has a gain \downarrow as and it ~~may~~ may be roll-off at high frequency;

* Roll-off occurs mainly due to the capacitive component in the circuit.

* This capacitive component is due to the physical characteristics of semi-conductor device and due to internal construction of op-Amp.

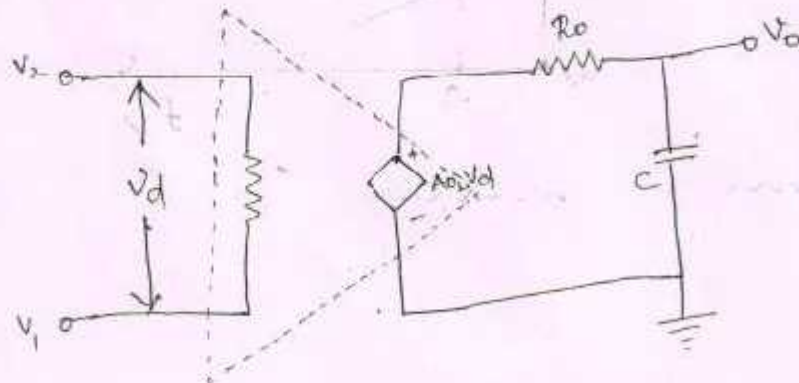
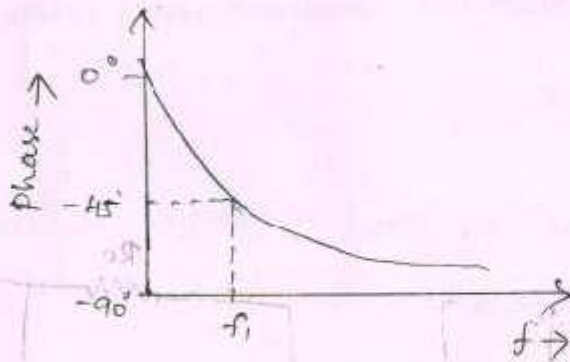
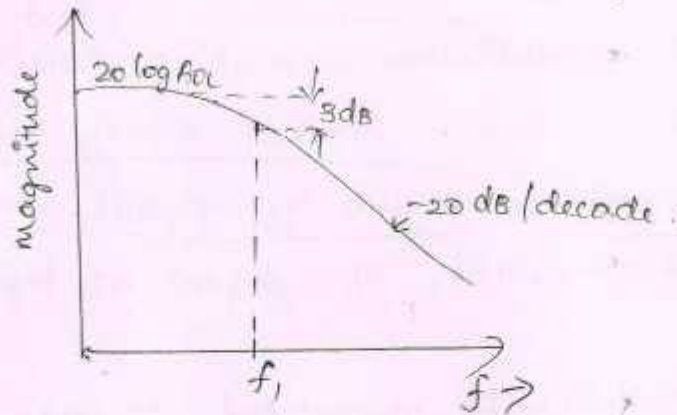


fig High frequency model of an op-Amp with single corner frequency.

The open loop voltage gain of an op-Amp with single corner ⁽²⁰⁾ frequency is,

$$A = \frac{A_{OL}}{1 + j(f/f_1)} \quad \text{where} \quad f_1 = \frac{1}{2\pi R_0 C}$$



* Frequency compensation! *

In order to obtain large bandwidth and low voltage gain, compensation is required.

There are mainly 2 types of compensation involved. They are

- External frequency compensation.
- Internal frequency compensation.

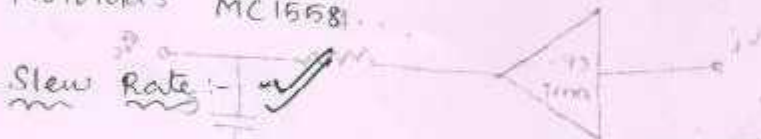
Internal compensation:-

→ In some applications, we require broad bandwidth, and to amplify slow changing signals.

→ For these applications, internally compensated op-Amps are used. These have internal shunt capacitance

→ The capacitance shunts off signal current and this reduces available op signal at higher frequencies.

Some internally compensated op-Amp's are Fairchild's $\mu A 741$, National Semiconductor's LM741, & Motorola's MC1558.



→ The rise time of an amplifier is the time, the op changes from 10% to 90% of the O/p for a step i/p.

→ Slew Rate is defined as the max rate of change of op voltage for a step i/p voltage.

Its unit is $V/\mu s$.

→ Slew Rate mainly caused due to capacitor within or outside the op-Amp. This prevents the op voltage from responding immediately to a fast changing i/p.

Slew Rate = $\frac{\Delta V_{op}}{\Delta t}$

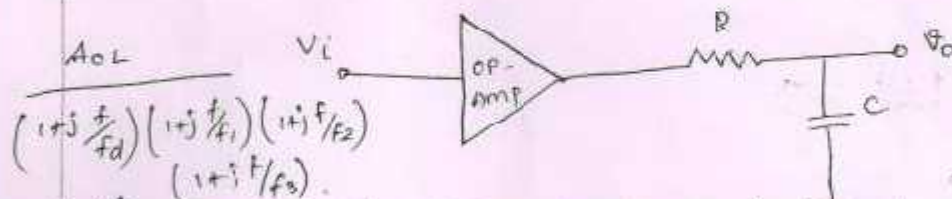
External frequency compensation is of 2 types. They are

- * Dominant - pole compensation.
- * Pole-zero compensation.

* Dominant - pole external compensation :- *

In External compensation method, compensating network is present externally to the circuit.

In dominant pole method, RC network may be added externally (or) suitable capacitor must be connected from a high resistance point to ground.



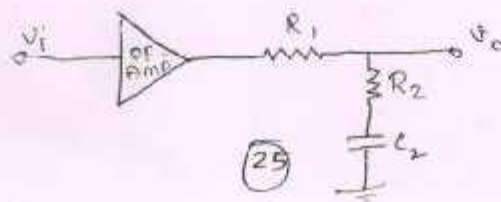
$$(1 + j\frac{f}{f_d}) (1 + j\frac{f}{f_1}) (1 + j\frac{f}{f_2})$$

$$(1 + j\frac{f}{f_3})$$

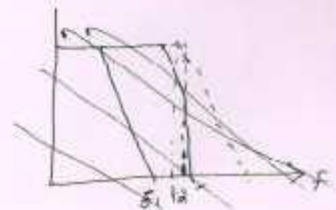
$f_1 < f_2 < f_3$ one disadvantage is that, it reduces open-loop bandwidth. But the noise immunity is improved

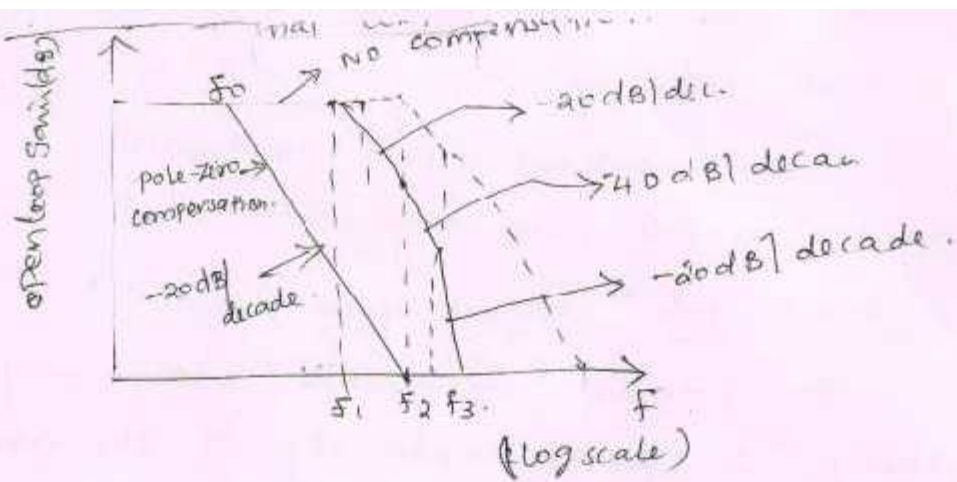
* Pole-zero external compensation :- *

Here the uncompensated transfer function is altered by adding both pole and zero. The zero should be at a higher frequency than pole



(25)



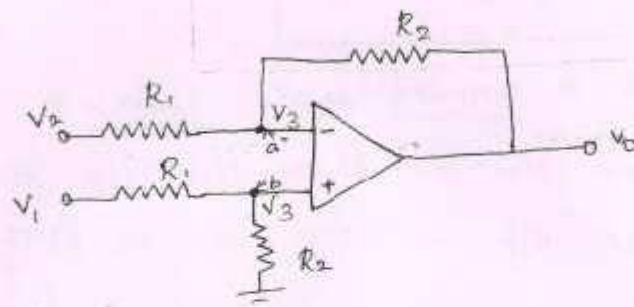


$$A' = \frac{A_{OL}}{(1 + j f/f_0)(1 + j f/f_2)(1 + j f/f_3)}$$

Differential Amplifier

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A ckt that amplifies the difference b/w 2 signals is called differential amplifier. This type is very much useful in instrumentation amplifier.



Since differential voltage at the ip terminal is zero, nodes 'a' and 'b' are at the same potential. The nodal eqn at 'a' is,

$$\frac{V_3 - V_2}{R_1} + \frac{V_3 - V_0}{R_2} = 0 \rightarrow \textcircled{1}$$

and at 'b' is,

$$\frac{V_3 - V_1}{R_1} + \frac{V_3}{R_2} = 0 \rightarrow \textcircled{2}$$

From eqn (1),

$$V_3 \left[\frac{1}{R_1} + \frac{1}{R_2} \right] - \frac{V_2}{R_1} = \frac{V_0}{R_2} \rightarrow \textcircled{3}$$

From eqn (2),

(2)

$$V_3 \left[\frac{1}{R_1} + \frac{1}{R_2} \right] - \frac{V_1}{R_1} = 0 \rightarrow \textcircled{4}$$

subtracting $\textcircled{4}$ from $\textcircled{3}$,

$$\frac{1}{R_1} [V_1 - V_2] = \frac{V_0}{R_2}$$

$$V_0 = \frac{R_2}{R_1} [V_1 - V_2]$$

* Difference mode & common-mode gain:- *

* If $V_1 = V_2$; then $V_0 = 0$, then the o/p gets cancelled and o/p is zero. This is true for ideal op-Amp.

→ But for practical op-Amp, exhibits some small response due to common mode component of i/p voltage.

→ The o/p voltage not only depends on the difference s/l, but also affected by average value of i/p s/l, called common-mode s/l (V_{cm})

$$V_{cm} = \frac{V_1 + V_2}{2}$$

In frequency domain, the eqn becomes,

$$V_o(s) = -\frac{1}{sR_1C_f} V_i(s)$$

Put $s = j\omega$,

$$V_o(j\omega) = -\frac{1}{j\omega R_1C_f} V_i(j\omega)$$

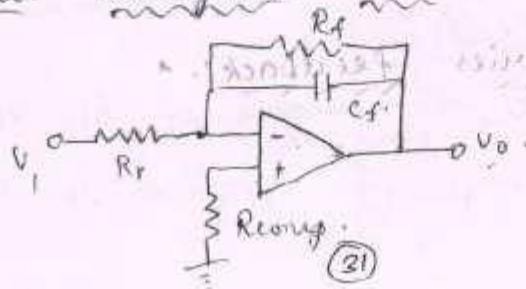
$$|A| = \left| \frac{V_o(j\omega)}{V_i(j\omega)} \right| = \frac{1}{\omega R_1C_f}$$

* Limitations: *

→ True integration is not possible because of the ^{presence of} offset voltage and bias current in the absence of i/p signal.

→ Small ac offset at the i/p, can force the o/p into saturation. To avoid this, resistor is placed in || with the capacitor.

* Practical integrator ckt: *



* For good differentiator, Time period 'T' must be greater than or equal to $R_f C_1$

$$T \geq R_f C_1$$

And it must follow the following

→ choose f_a equal to the highest frequency of the i/p signal. Assume practical value of $C_1 < 1 \mu F$ & calculate R_f

→ choose $f_b = 10 f_a$. calculate the value of R_1 & C_f , so that $R_1 C_1 = R_f C_f$.

* Applications :- *

- The differentiators are used in waveshaping circuits.
- They are used as Edge detectors in FM demodulators.
- They are used in combination with adders and amplifiers to form analog computers.

* Integrators :- *

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→ Integrator ckt is a ckt, in which

* Applications :- *

- They are used in combination with adders and amplifiers to form analog computers.
- They are used in waveshaping
- They are used for solving differential equations in A/D converters & ramp generators.

Voltage Series feedback amplifier :- * SESSION-13

Depending upon whether voltage / current is fed back either in series or in ||, there are 4 types of fb connections. They are

- Voltage Series feedback.
- Voltage shunt fb
- current Series fb
- current shunt fb

Voltage Series feedback :-

In this ckt a sample of O/P voltage connected in series in opposition to the i/p

