

# SRI VIDYA COLLEGE OF ENGINEERING & TECHNOLOGY COURSE PLAN (THEORY)



									Λ.	CADEM	IIC V	EAD	. 2018	10
Subject Code				E	E6601				A	CADEM	L	P	T	19 C.
Subject Title			SC	DLID STA	ATE DRI	VES			3	0	0	3		
Year / Dept / Sem									Reg	ulation \	Vear			
Faculty Name / Desg / Dept					III / EEE / VI Regulation Year 2013  Ms.K.PADUKOLAI / Asso Professor / EEE									
Course Prereq		37 Dept					TERM IN		cal And	Electro	nico	Engi	nooring	
Course Frerey	luisite				The same of the sa	dge in P				Electro	THES	⊏ngı	neening	
					Att	ach the	copy of s	yllabus						
				C	O1: To	understa	and stea	dy state	e operat	ion and	tran	sient	dynam	ics of
				a motor load system										
				CO2: To study and analyze the operation of the converter/chopper fed dc drive, both qualitatively and quantitatively.										
0	····· (i	70)		CO3: To study and understand the operation and performance of										
Course Object	iives (C	.0)		induction motor drives.										
				CO4: To study and understand the operation and performance of										
				synchronous motor drives.										
				CO5: To analyze and design the current and speed controllers for a closed loop solid state DC motor drive.										
				At the end of the course, the students should be able to:										
				ECO1:Understand the steady state operation and transient dynamics o										
				a motor load system  ECO2: Understand the the operation of the converter/chopper fed dc										
Expected Cou	rse Ou	tcomes		drive, both qualitatively and quantitatively.										
(ECO)				ECO3: Understand the operation and performance of induction motor										
				drives.  ECO4: Understand the operation and performance of synchronous										
				motor drives.  ECO5: Understand to design the current and speed controllers for a										
				closed loop solid state DC motor drive.										
· · · · · · · · · · · · · · · · · · ·	Mappin	ng of CC	) & P	0(		The second second second			with the		given	belo	w)	
	PO1	PO2	PO3		PO4	PO5	PO6	PO7	PO8	PO9	PC	10	PO11	PO1
CO1	2		2		-	2	- 1	-	-	-			-	-
CO2	1	3	3		3		1	2	3	-				
CO3	1	3	1		-			-		-				
· CO4	2 .	1	2	Part i	3					-				-
CO5	2	1	3			-	3	3	3	_		-		-

(Additional Topics beyond syllabus/Seminars/Assignments)	
Related Website URLs	W1: https://www.scribd.com/doc/274734114/255722651- Fundamentals-of-Electric-Drives-GK-Dubey-Copy-Copy-pdf W2: http://nptel.ac.in/courses/webcourse-contents/IIT W3:https://docs.google.com/file/d/0B_gTrLYkYZgzWTBvN0NSVIhD Mms/edit W4: http://kaliasgoldmedal.yolasite.com/resources/SSD
Related Video Course Materials (min. 3 nos)	V1: http://nptel.ac.in/courses/108105067/ V2: http://www.learnerstv.com/Free-Engineering-Video-lectures-ltv230-Page1.htm. V3: http://nptel.ac.in/courses/108108077/12

S.No	Topic Name	Book & Page no	Mode of delivery	No of hrs	Cumulative hrs .	
		VE CHARACTI	ERISTICS			
1.	Introduction	Notes	×	1	1	
2.	Electric drive	R7-1.2	PPT	1	2	
3.	Equations governing motor load dynamics	1.8		1	3	
4.	steady state stability	1.19		. 1	4	
5.	Typical load torque characteristics	1.10		1	5	
· 6.	Multi quadrant	1.13		2	7	
. 7.	Dynamics: acceleration, deceleration, starting & stopping	1.21		2	8	
8.	Selection of motor	1.4		1	9	
	UNIT II - CONVERTER /	CHOPPER FEI	DC MOTOR DRI	VE		
.9.	Introduction	Notes	1	1	10	
10	DC motor,types	R7-2.1-2.4	PPT	2	11 .	
11	Speed and Torque equation	2.5-2.7		1	12	
12		2.7-2.14		1	13	
	Conventional speed control of DC motor	2.15-2.28		2	15 .	
14		2.29		1	16	
15.		2.30-2.57	<b>V</b>	2	18	
16.		2.80-2.84		2	20	
17	Dual converter	2.91-2.96		1 _	21	
18.	Time ratio and current limit control	3.9-3.12		1_	22.	
	4 quadrant operation of chopper fed drive.	3.1-3.8		3	25	
17,1		UCTION MOTO	R DRIVES			
20	Introduction	R7-5.1-5.17		1	26 .	
.21	Stator voltage control	5.23-5.30		2	27	
22		5.63-5.70		2	29 .	
23		5.75		2	31	
24	voltage source fed inverter	5.78-5.83		1	32 .	
25	Current source fed inverter	5.86-5.88		1	33	
		5.88-5.91		1	34	
20	UNIT IV - SYNCE		OR DRIVES			
27	Introduction	R7-6.1-6.8			35	

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· 28				1	36
. 29		6.11		2	38
· 30	Margin angle control	6.13		2	. 40
31.	power factor control	6.22		1	41 '
32.	32 permanent magnet synchronous motor.		PPT	2	43
	UNIT V - PERMANENT	MAGNET SYN	CHRONOUS MC	TORS	
33.		R7-4.1	14	1	44
34.	closed loop control of electric drive	4.1-4.4	Video	1	45
35.	closed loop control with speed feedback-armature voltage control and field weakening mode	4.4		1	46
. 36.		4.12		2	48
. 37.	speed controller	4.15		2	50
38.	Current controller	4.19		1	51
. 39.	. 39 converter selection and characteristics.			1	52

	Prepared by	Approved by
Signature	12	Dearnaignes.
Name	Ms.K.PADUKOLAI	Mr.P.I.D.T.BALA DURAI KANNAN
Designation	Asso Professor / EEE	Assistant Professor & HOD /EEE
Signed date	23.10.18	23/2018

#### LEGEND:

# METHODOLOGY TO MAP OBJECTIVE WITH OUTCOMI

Course outcomes are achieved through

- a. Class room teaching.
- b. Assignments.
- c. Tutorials
- d. Weekly, monthly and model exams.
- e. Seminars

# **TEXT BOOKS:**

- 1. Gopal K.Dubey, Fundamentals of Electrical Drives, Narosa Publishing House, 1992.
- 2. Bimal K.Bose. Modern Power Electronics and AC Drives, Pearson Education, 2002.
- 3. R.Krishnan, Electric Motor & Drives: Modeling, Analysis and Control, Prentice Hall of India, 2001.

### REFERENCES:

- 1. John Hindmarsh and Alasdain Renfrew, "Electrical Machines and Drives System," Elsevier 2012.
- 2. Shaahin Felizadeh, "Electric Machines and Drives", CRC Press(Taylor and Francis Group), 2013.
- 3. S.K.Pillai, A First course on Electrical Drives, Wiley Eastern Limited, 1993. .
- 4. S. Sivanagaraju, M. Balasubba Reddy, A. Mallikarjuna Prasad "Power semiconductor drives" PHI, 5th printing, 2013.
- 5. N.K.De., P.K.SEN"Electric drives" PHI, 2012.
- 6. Vedam Subramanyam, "Thyristor Control of Electric Drives", Tata McGraw Hill, 2007.
- 7.J.Gnanavadivel, Dr.J.karthikeyen, B.santhi, "solid state drives" Anuradha publications,

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Page 3 of 3

## **OBJECTIVES:**

- To understand steady state operation and transient dynamics of a motor load system.
- To study and analyze the operation of the converter/chopper fed dc drive, both qualitatively and quantitatively.
- To study and understand the operation and performance of AC motor drives.
- To analyze and design the current and speed controllers for a closed loop solid state DC motor drive.

#### UNIT I DRIVE CHARACTERISTICS

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Electric drive – Equations governing motor load dynamics – steady state stability – multi quadrant Dynamics: acceleration, deceleration, starting & stopping – typical load torque characteristics – Selection of motor.

# UNIT II CONVERTER / CHOPPER FED DC MOTOR DRIVE

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Steady state analysis of the single and three phase converter fed separately excited DC motor drive—continuous and discontinuous conduction— Time ratio and current limit control — 4 quadrant operation of converter / chopper fed drive.

#### UNIT III INDUCTION MOTOR DRIVES

9

Stator voltage control-energy efficient drive-v/f control-constant airgap flux-field weakening mode – voltage / current fed inverter – closed loop control.

#### UNIT IV SYNCHRONOUS MOTOR DRIVES

9

V/f control and self control of synchronous motor: Margin angle control and power factor control – permanent magnet synchronous motor.

# UNIT V DESIGN OF CONTROLLERS FOR DRIVES

Transfer function for DC motor / load and converter – closed loop control with Current and speed feedback–armature voltage control and field weakening mode – Design of controllers; current controller and speed controller- converter selection and characteristics.

- Ability to understand and apply basic science, circuit theory, Electro-magnetic field theory control theory and apply them to electrical engineering problems.

  TEXT POONS:
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